



Systems and Internet
Infrastructure Security

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On Dynamic Malware Payloads Aimed at Programmable Logic Controllers

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SCADA and PLCs

- PLCs are the lowest level of computation in the SCADA system

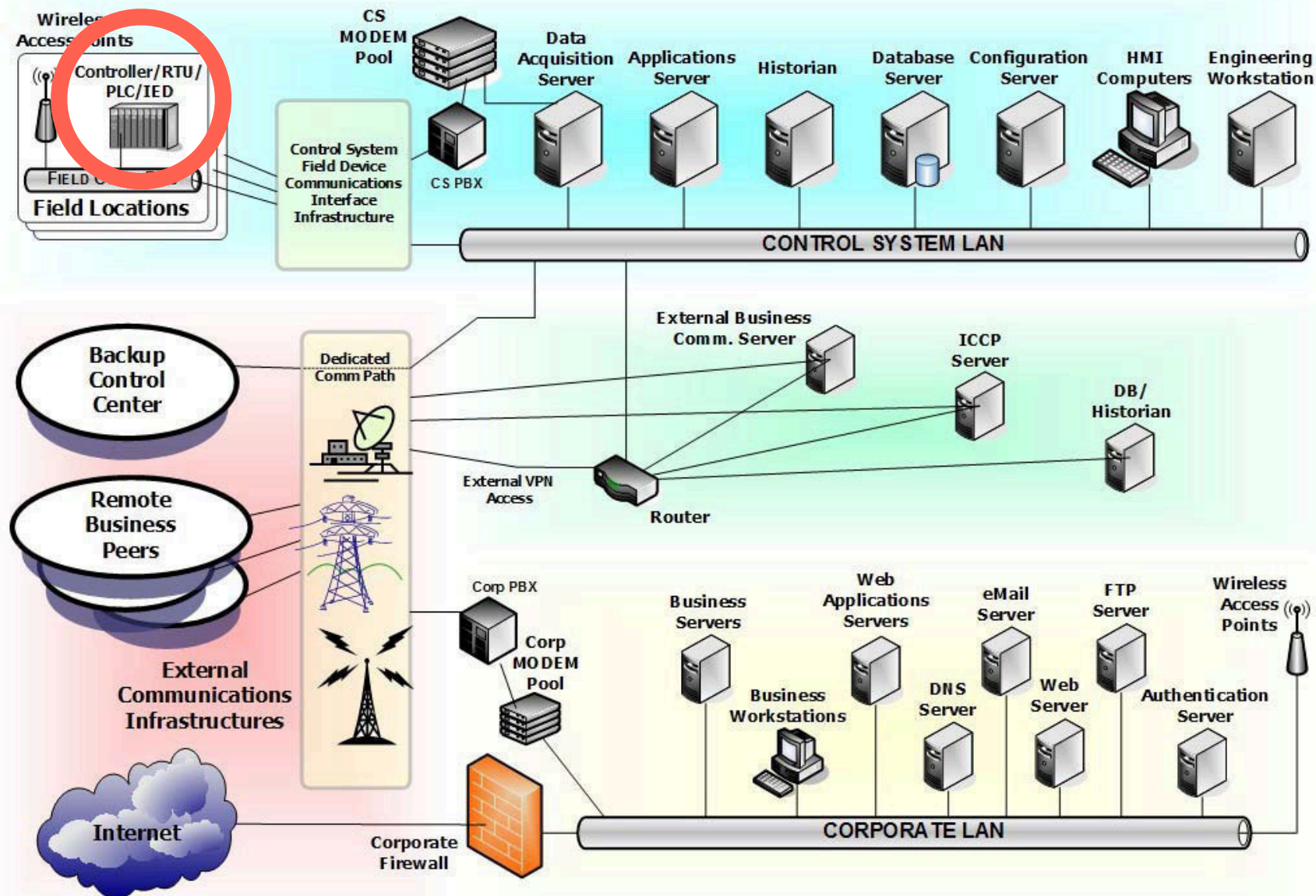


Image source: *Control Systems Cyber Security: Defense in Depth Strategies*. Idaho National Laboratory. 2006

Stuxnet's PLC payload

Stuxnet delivered a *precompiled payload*. The specifics details of the target had to be known ahead of time.

Against any other target, the payload would have random or no affect.

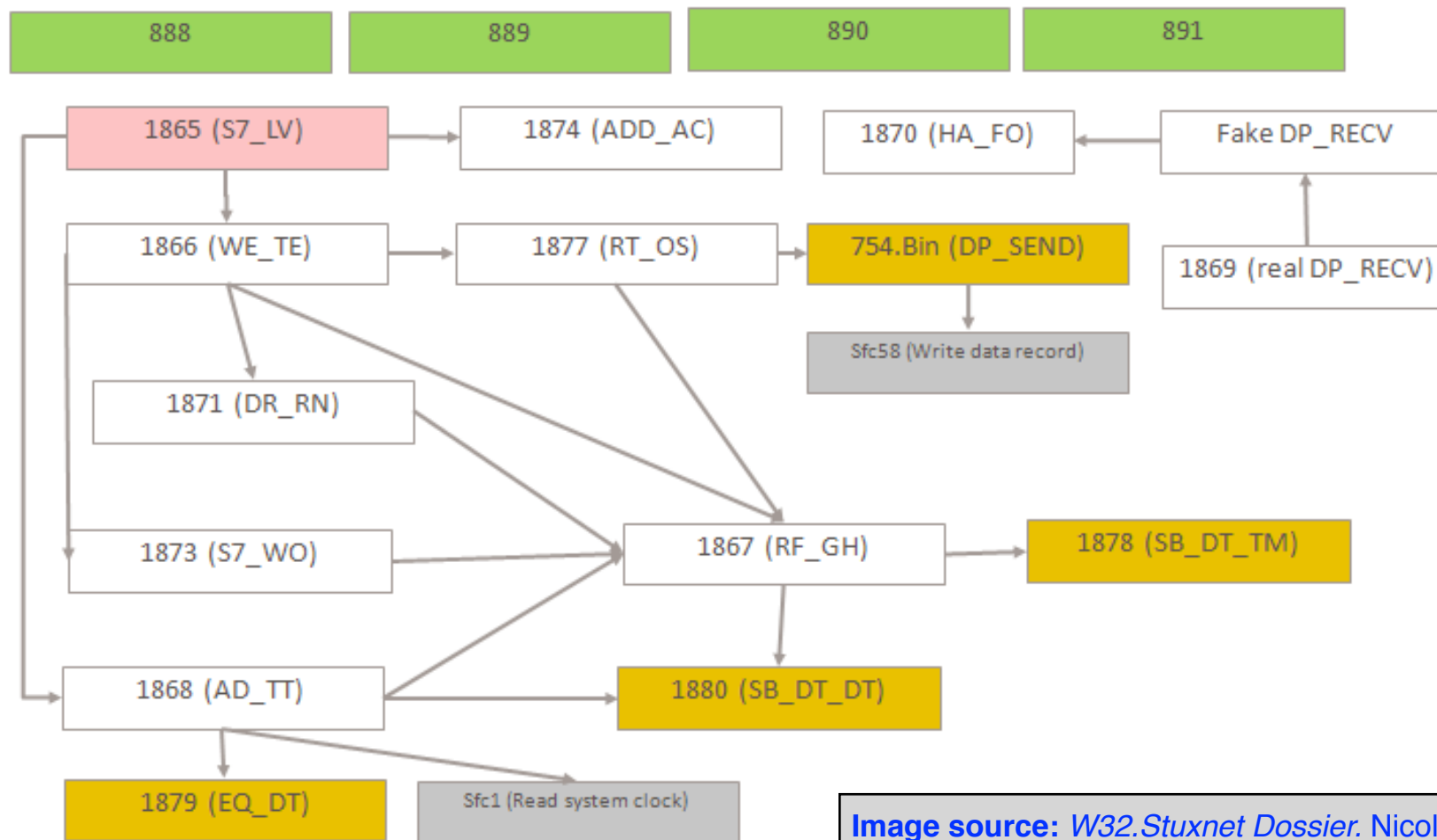
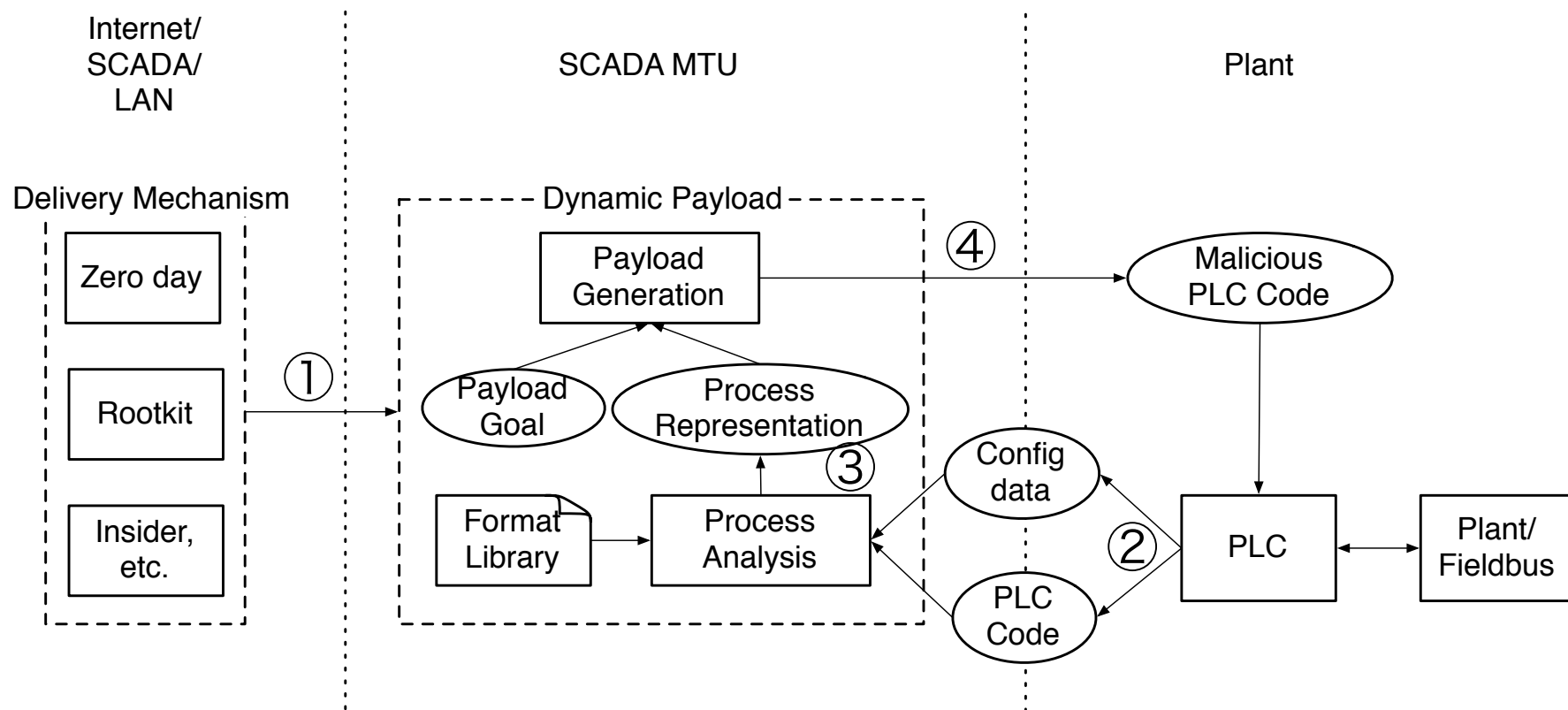


Image source: *W32.Stuxnet Dossier*. Nicolas Falliere, et al. 2010

Are dynamic payloads for unknown or partially known targets possible?

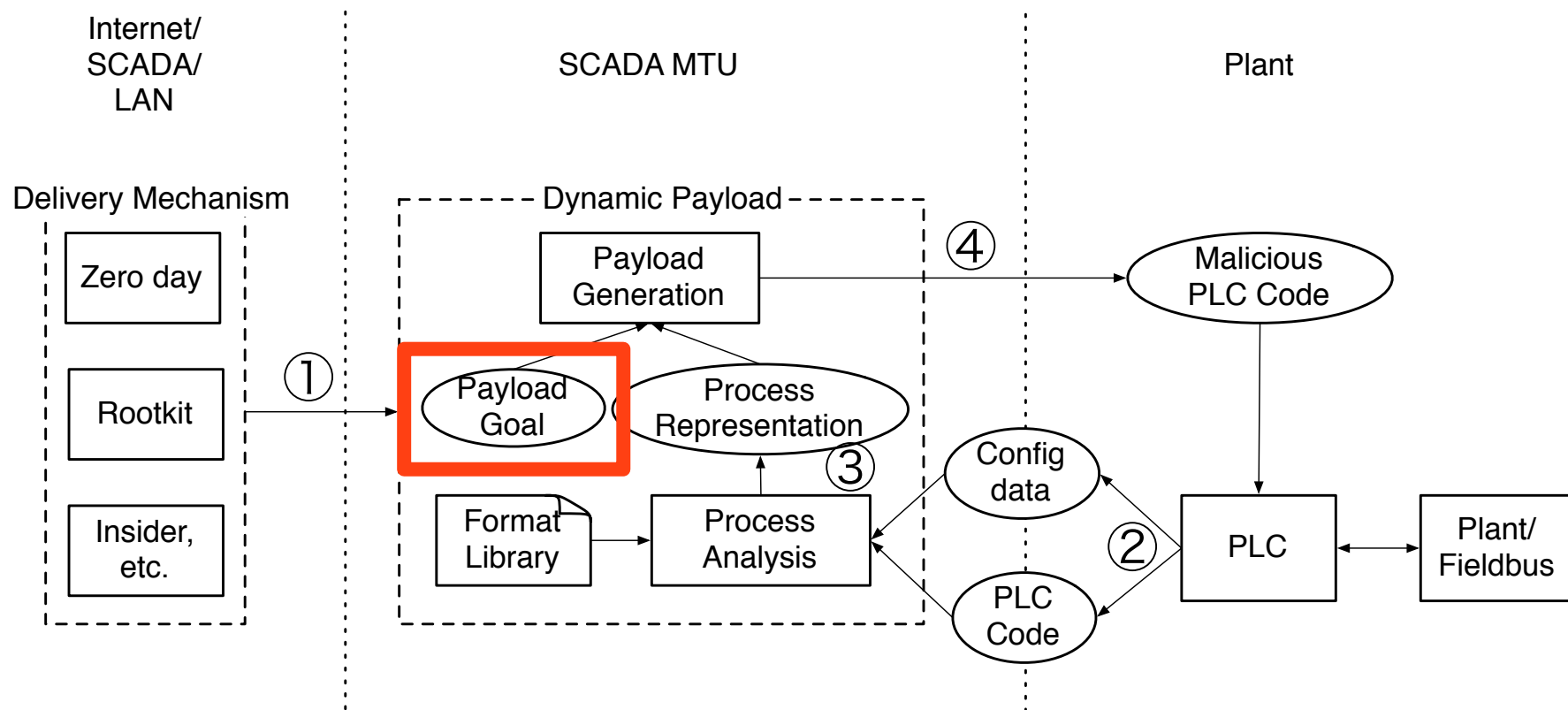
An engineering problem

- Writing malware to overcome the obscurity of process control systems is an engineering problem.



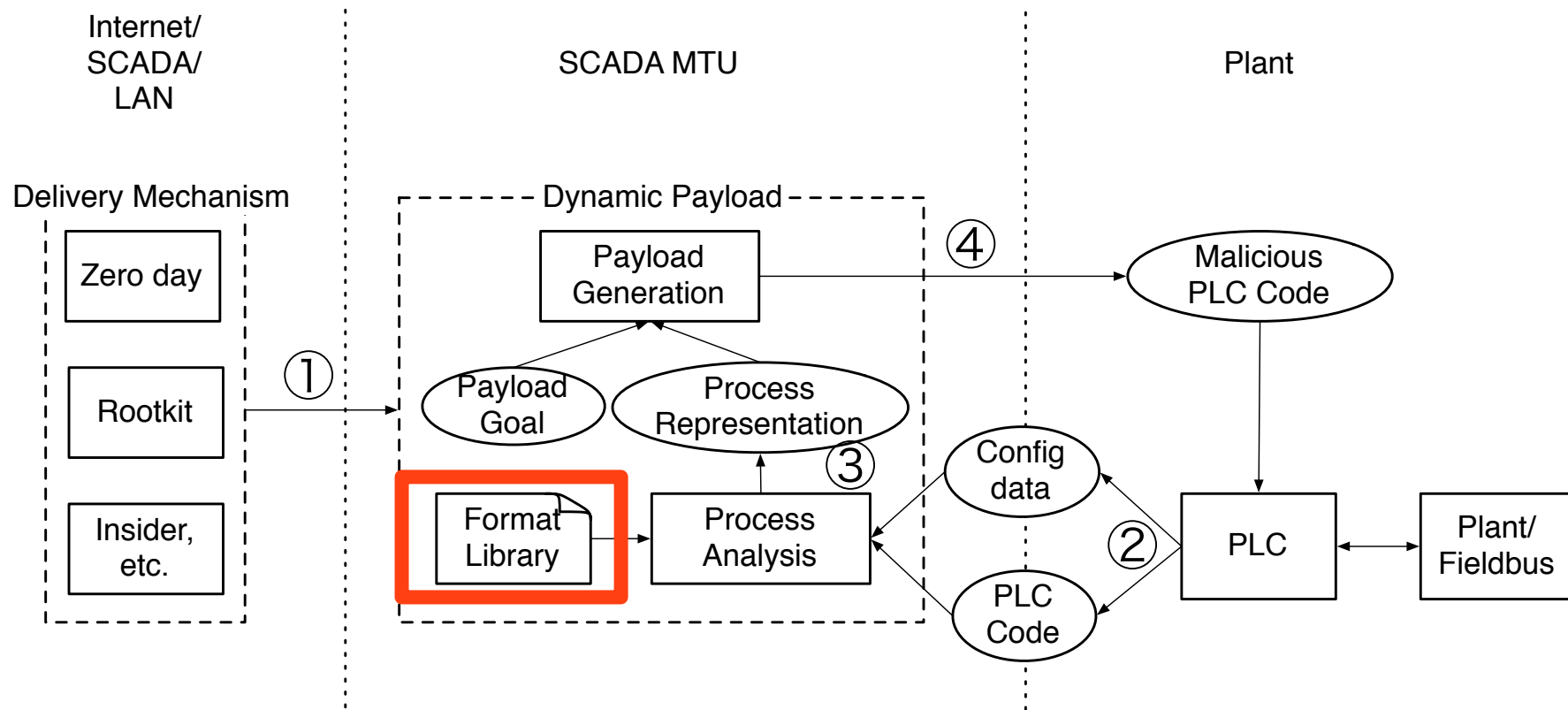
- This problem can be solved, as can all software engineering problems, through a breaking down into modular steps.

Ideally, the adversary need only specify the payload goal.



Code reuse

The format library contains platform-depended disassemblers and device IDs.



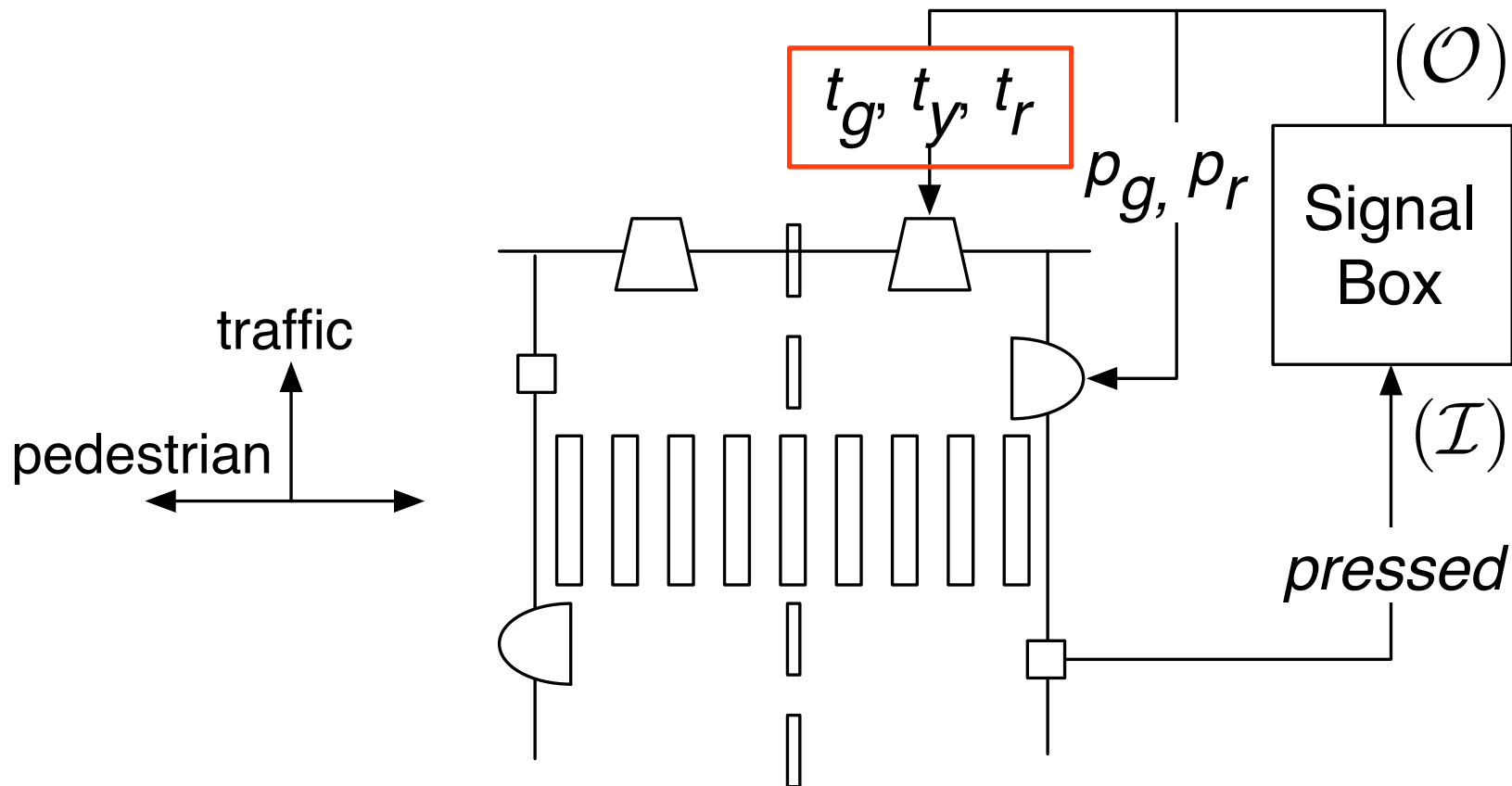
Logic programming

- Logic programs simulate Boolean circuits.
- A PLC program maps a set of input variables \mathcal{I} to a set of output variables \mathcal{O} .
- Values for \mathcal{I} are received from the sensors in the plant, and values in \mathcal{O} are sent to the plant to manipulate devices.
- A set of internal state variables \mathcal{C} and timer variables \mathcal{T} are also available.
- A logic program is a set of expressions Φ s.t.

$$\forall (y \leftarrow \phi) \in \Phi, \text{Var}(\phi) \subseteq \mathcal{I} \cup \mathcal{O} \cup \mathcal{C} \cup \mathcal{T} \text{ and } y \in \mathcal{O} \cup \mathcal{C} \cup \mathcal{T}$$
- Note that in practice, we can often differentiate the four types of variables.

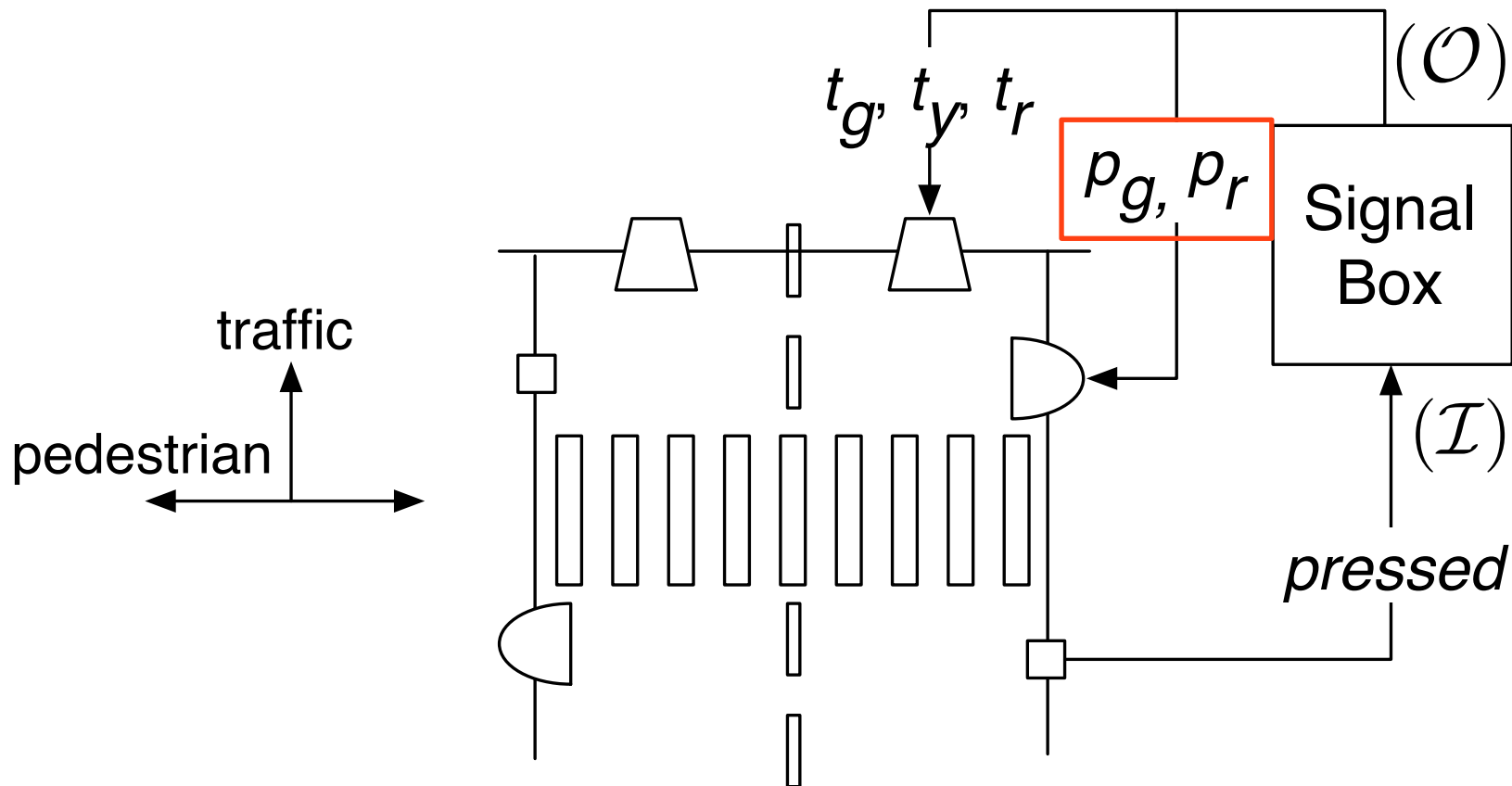
A pedestrian crossing

Traffic green, yellow, and red (output)



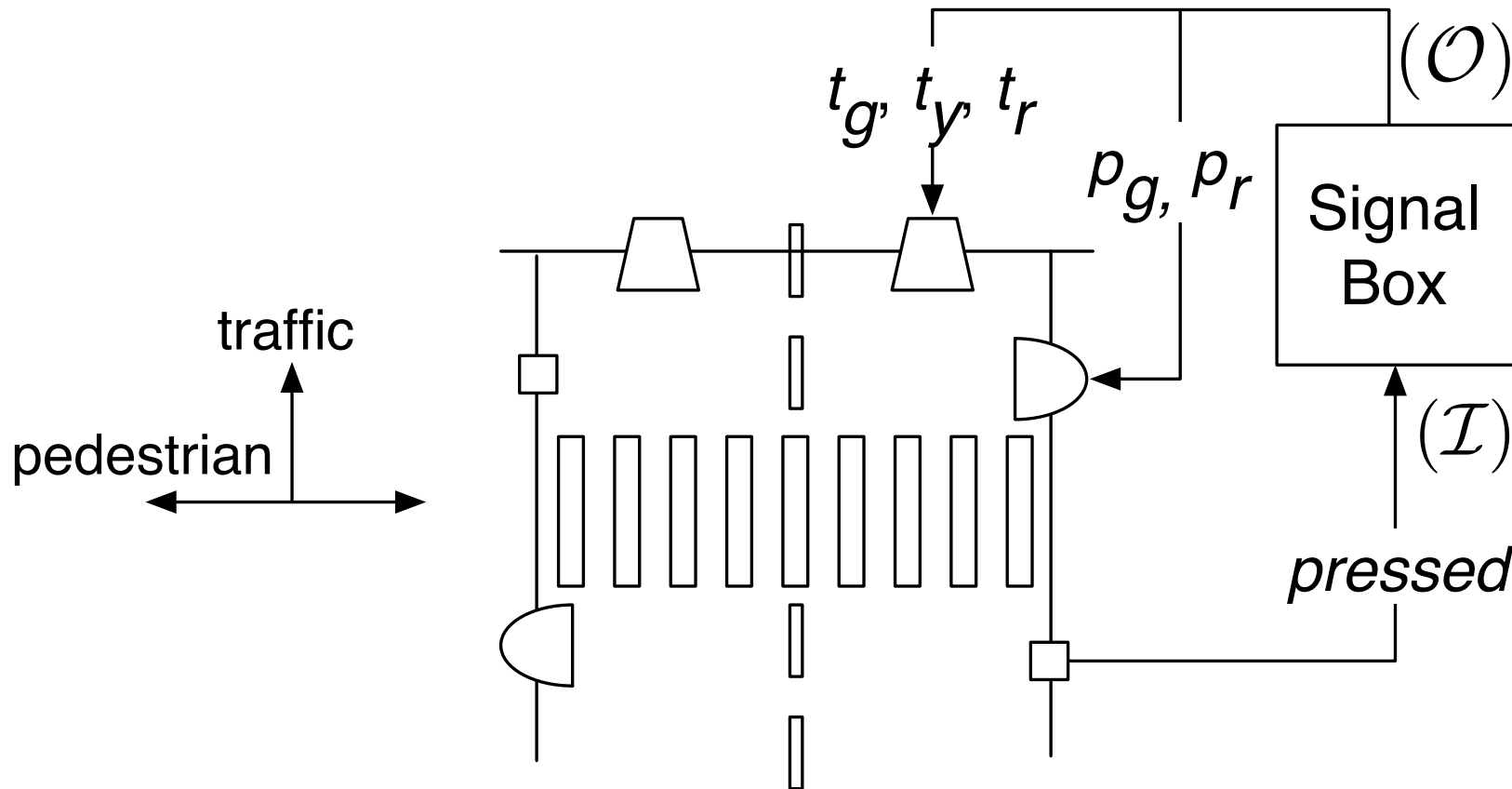
A pedestrian crossing

Pedestrian green and red (output)

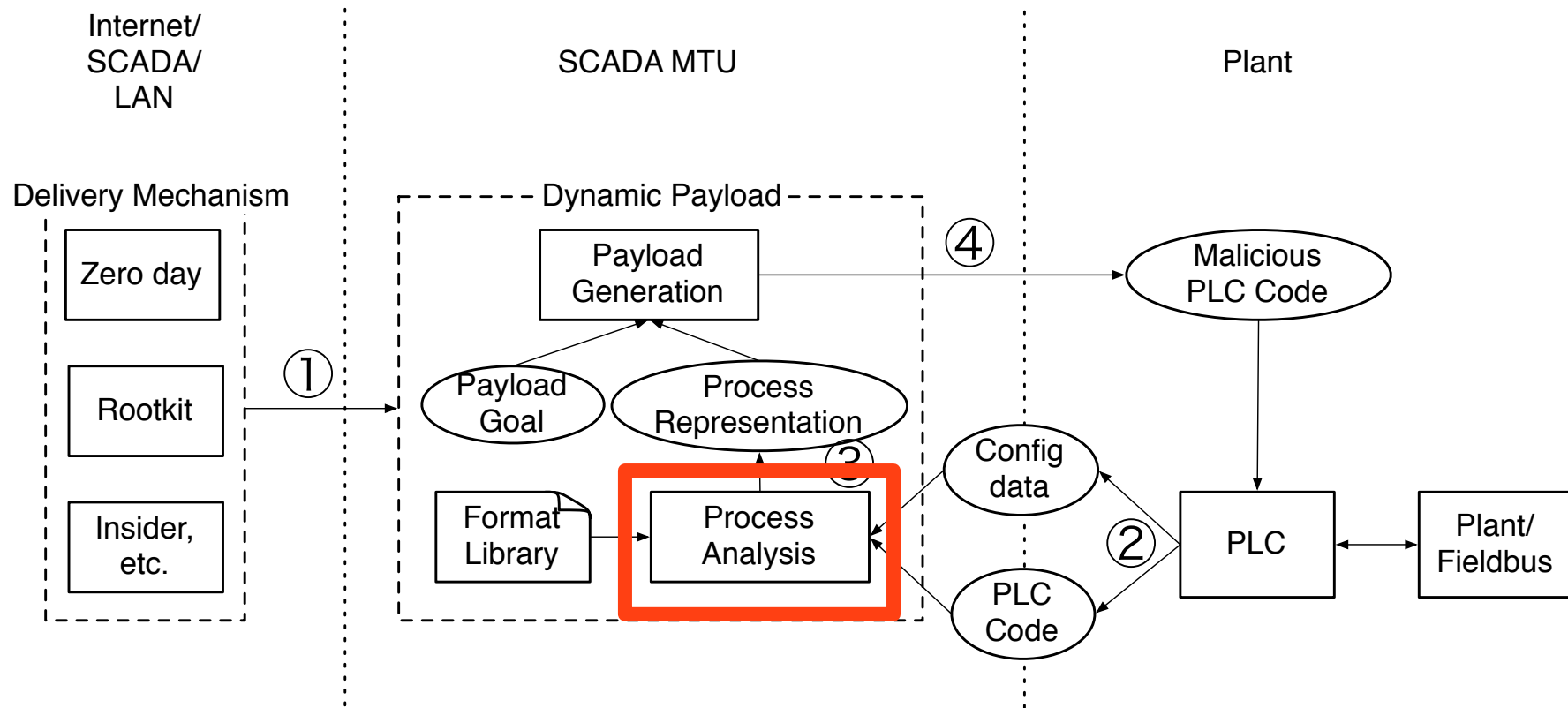


A pedestrian crossing

$$(y \leftarrow \phi) = (p_g \leftarrow pressed \wedge t_r), \quad \text{Var}(\phi) = \{pressed, tr\}$$



Process analysis



- How do we obtain the canonical process representation from the binary logic?
- While PLC ISAs differ between vendors, many implement the accumulator based architecture specified by the IEC 61131-3 *Instruction List* (IL) language.
- Thus, converting code to a canonical format of Boolean expressions Φ requires two steps:

Binary code \longrightarrow IL code \longrightarrow Boolean expr's

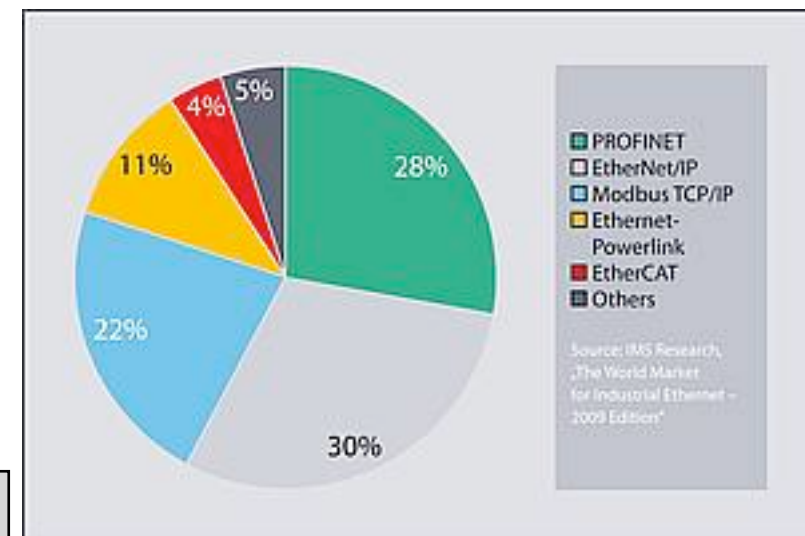
Disassembly: Using a mapping from the format library.

Logic recovery: We have implemented in < 200 lines of Standard ML.

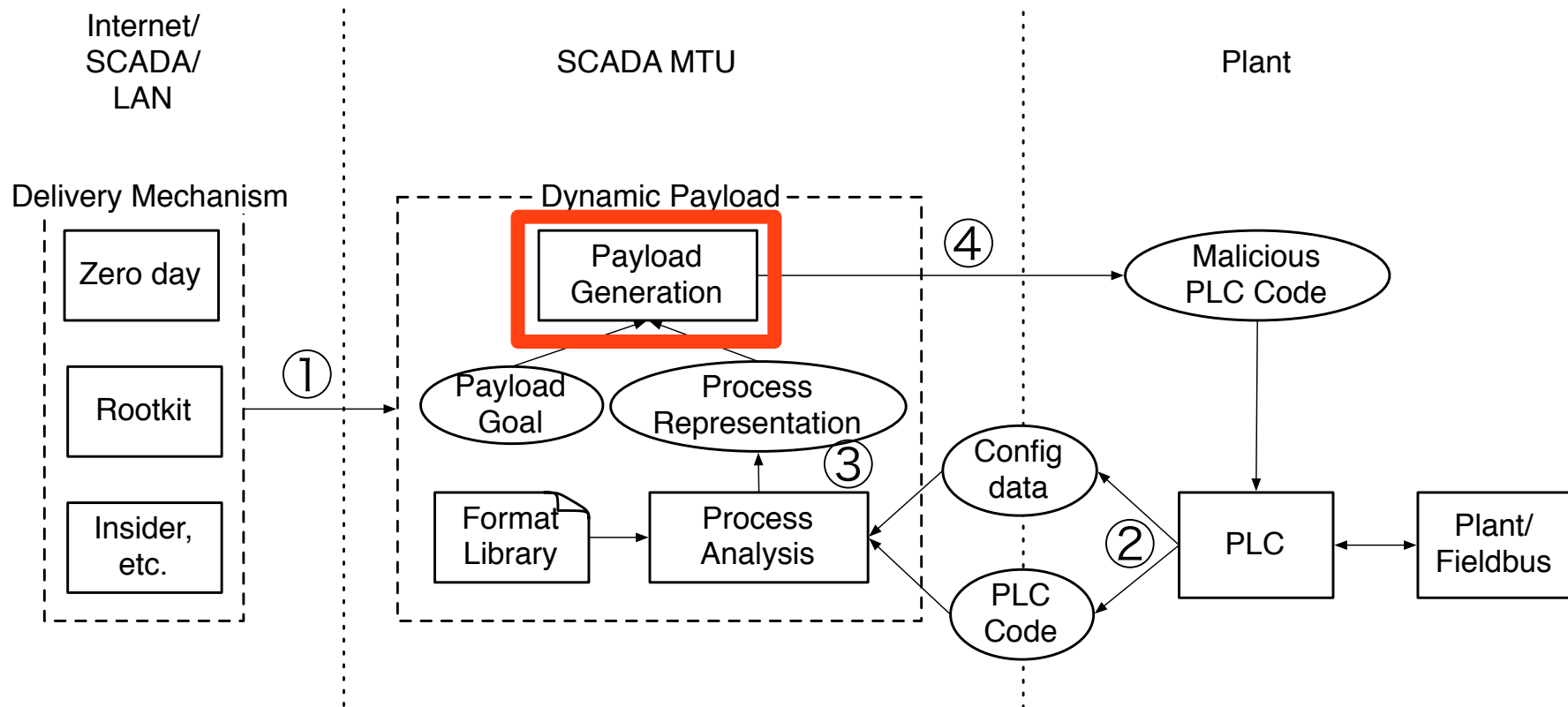
Process analysis: configuration data

- PROFINET and PROFIBUS both network PLCs to devices with some onboard intelligence.
- Each PROFI* compliant product has a unique ID that can be queried.
- Stuxnet looked for centrifuge IDs.
- A database of such IDs can be used to map logic variables to physical devices.
- PROFI* device IDs can be scraped from reseller product list, .GSD files, and profibus.com.
- Collect them all!

Image source: profibus.com



Payload generation



Inferring device *types*

- Will not always be possible to learn devices from PROFIBUS, PROFINET, etc.
- However, if the class of plant under attack is known, certain domain specific invariants will link variables of interest.
- For example:
 - ▶ A time delay of a few seconds is enforced before a motor can reverse directions.
 - ▶ Electrical substation switchgear state changes must be executed in specific orders.
- Of course, this requires that the adversary have some domain specific knowledge of the target, but no target specific knowledge is needed.

Safety interlocks

- Safety interlocks are invariants over the outputs of a control system that must never be violated
- Pedestrian crossing interlock:
 - ▶ Let p_g and t_g be the Boolean variables for the pedestrian green light and the traffic green light respectively
 - ▶ Regardless of the particulars of the light scheme, the following must hold:

$$\neg(p_g \wedge t_g)$$

- ▶ May be explicit: The property is stated as a check in the logic
- ▶ Or implicit: The property is never violated by the logic

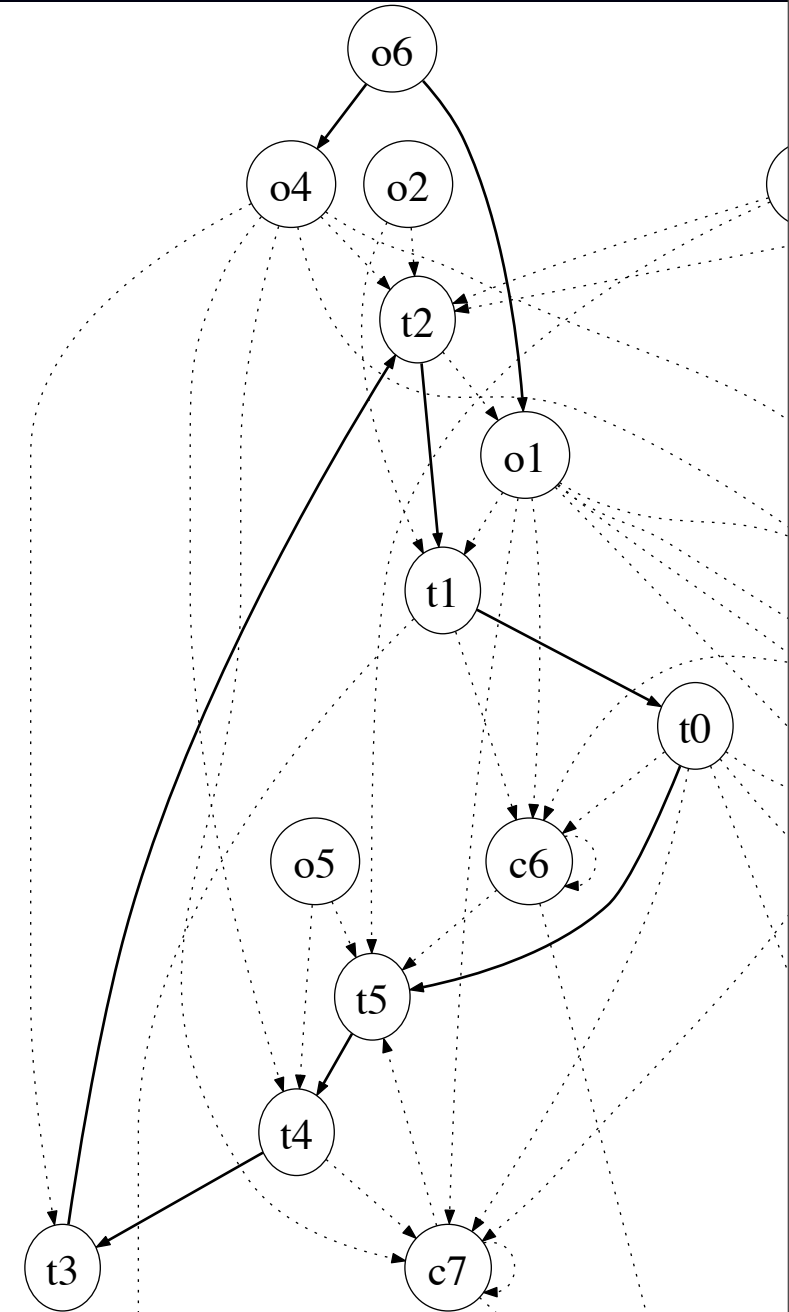
- To exploit a safety interlock, the malware must
 - ▶ 1. Extract the interlock
 - ▶ 2. Find an assignment to some subset of \mathcal{O} that violates the interlock
 - ▶ 3. Send that assignment to the plant
- Extracting explicit interlocks requires finding the set:
$$\{(y \leftarrow \phi) \in \Phi \mid y \in \mathcal{O} \text{ and } \text{Var}(\phi) \cap \mathcal{O} \neq \emptyset\}$$
- Extracting implicit interlocks requires verification techniques
 - ▶ Thus, rewriting logic to contain only implicit interlocks can make interlock exploitation harder

Inferring process structure

- Some processes tend to be more **event-driven** while others are more **logic-driven**.
- The latter is most common in manufacturing, traffic control, and sequence control applications.
- For logic-driven processes, extracting the main loop can be useful for a number of things:
 - ▶ Determining where to hook malicious code
 - ▶ Finding terminal states, especially those that depend only on outputs. (These are indicative of alarm conditions.)

Process dependency graph

- Data dependency graph for logic variables.
- Only the class of a variable is known (input, output, state, or timer).
- In this example (traffic light system):
 - ▶ The main timing loop can be seen.
 - ▶ o6 (alarm condition) is interlocked to o4 and o1 (conflicting green lights).



- The individual tasks needed for constructing dynamic malware payloads seem feasible.
- Arguably, the hardest and most expensive task is the collection of disassemblers and device databases.
- Plants can be forced to behave unsafely even if no device information is available.
- Malware authors can leverage existing program analysis techniques like dependency graphs to design dynamic payload mechanisms.
- *We are looking for test cases!*

Thanks!

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